

GCE AS LEVEL – COMPUTER SCIENCE UNIT 1 QUESTION PACK

2500U10-1 · 2015 spec Unit 1 Topic 6 · AS unit, first sat 2017, 100 marks, 2h paper

REVISE.wales**COMPUTER SCIENCE – UNIT 1 · Algorithms – Searching, Sorting & Trace**

Topic 1.5 – Algorithm design, linear and binary search, bubble sort, dry-running and compression

Writing pseudo-code algorithms with appropriate constructs and identifiers, tracing algorithms to predict output, fixing logic errors in bubble-sort and other code, comparing linear and binary search, and the principles of data compression.

2015 specification · current

Estimated time for entire question pack: ~2 h 26 min

Derived from the Unit 1 pace of ~1.2 min/mark, padded for written-prose answers (97 marks over 12 questions).

*You are advised to **not** attempt to complete all of this in one sitting.*

ABOUT THIS QUESTION PACK

This is a **comprehensive topic question pack**, not a single mock paper. It contains every question from the WJEC AS Unit 1 papers (Summer 2017 – Summer 2024, COVID gap) that maps onto Topic 1.5 of the 2015 specification.

Questions are ordered by source paper date.

INSTRUCTIONS

Use black ink or black ball-point pen. Show all working. A calculator is allowed where useful.

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Q	Source	Max	Mark
1	S17 Q10	8	
2	S17 Q12	4	
3	S18 Q8	8	
4	S18 Q9	9	
5	S18 Q10	11	
6	S19 Q2	6	

Q	Source	Max	Mark
7	S19 Q10	13	
8	S22 Q10	8	
9	S23 Q7	8	
10	S23 Q10	6	
11	S24 Q5	8	
12	S24 Q9	8	
Total		97	

Algorithms – Searching, Sorting & Trace – what the spec asks

WJEC GCE AS Computer Science (from 2015) · Unit 1: Fundamentals of Computer Science · Topic 1.5.

Algorithm design

- Use self-documenting identifiers (e.g. total, count, isPrime).
- Indent control structures consistently.
- Combine sequence, selection (IF / CASE) and iteration (WHILE / FOR / REPEAT).
- Validate input early; handle edge cases (empty, single, max).

Linear search

- Walk array start-to-end comparing each element to target.
- $O(n)$ time; works on unsorted data.
- Best for small or unsorted lists.
- Worst case = whole list scanned with no match.

Binary search

- Requires sorted array; repeatedly halves the search range.
- Compare middle element with target; recurse / iterate on left or right half.
- $O(\log n)$ time; large speed-up for big sorted lists.
- Maintain start, end, mid pointers; terminate when start > end (not found).

Bubble sort

- Repeatedly pass through list, swap adjacent out-of-order pairs.
- After each pass, largest element is at end (its final position).
- $O(n^2)$ worst case; $O(n)$ if already sorted with 'swapped' flag.
- Simple but slow for large lists; useful pedagogically.

Insertion sort

- Builds sorted sublist one element at a time.
- Each new element shifted backwards into its position.
- Efficient for small or nearly-sorted lists.
- $O(n^2)$ worst case but in-place and stable.

Compression principles

- Lossless: reversible; e.g. run-length encoding, Huffman, ZIP.
- Lossy: discards perceptually unimportant data; e.g. JPEG, MP3.
- Trade-off: smaller files vs computational cost (and quality for lossy).
- Dictionary methods replace repeated substrings with short codes.

Algorithms – Searching, Sorting & Trace in one page

Quick-reference notes – revisit before each question.

Pseudocode conventions

Use named procedures, clear identifiers, indented control structures. FOR / WHILE / REPEAT, IF / THEN / ELSE, CASE.
Declare types of variables.

Linear vs binary

Linear: any list, $O(n)$.
Binary: sorted only, $O(\log n)$.
1024 items: linear ~1024 steps; binary ~10 steps.

Bubble sort with flag

Repeat passes through array.
If a pass makes no swaps (flag stays false) \Rightarrow sorted, exit early.
Best $O(n)$, worst $O(n^2)$.

Dry-running

Trace table: columns for each variable + output.
Step through every iteration.
Spot infinite loops, off-by-one, missing increments.

Algorithm debugging

Identify the bug: trace; check loop bounds; check initialisation; check IF conditions; check parameter passing.
State the line and the fix.

Compression types

Lossless: ZIP, PNG, FLAC – reversible.
Lossy: JPEG, MP3, MP4 – smaller, irreversible quality loss.

12. Describe how bubble sort and insertion sort algorithms operate.

[4]

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10. The following bubble sort algorithm attempts to sort integers stored in myArray, but contains an error.

```
1 Start Procedure SortMyArray
2 n is integer
3 temp is integer
4 swapped is boolean
5
6 set n = length(myArray) {returns the length of myArray}
7 repeat
8   set swapped = FALSE
9   for i = 0 to (n - 1)
10    if myArray[i] < myArray[i + 1] then
11      temp = myArray[i + 1]
12      myArray[i + 1] = myArray[i]
13      myArray[i] = temp
14      swapped = TRUE
15    end if
16  end for
17 until (swapped = TRUE)
18
19 End Procedure
```

(a) Suggest appropriate test data to dry-run this type of algorithm in order to identify possible errors. [3]

Test Data Set 1

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Test Data Set 2

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Test Data Set 3

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(b) Describe how a bubble sort algorithm should operate. [2]

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(c) Explain why the bubble sort algorithm in this question will fail.

[2]

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(d) Suggest a suitable change that could be made to the algorithm to overcome this problem.

[1]

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(e) Name and describe a different sort algorithm.

[3]

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2. This is an algorithm which should have four outputs, a, b, c and d. The algorithm does not work as intended.

```
1  define myFunction
2  declare c as integer
3  declare d as integer
4      set c = 3
5      set d = 4
6  end myFunction
7
8  Start MainProg
9  declare a as integer
10 declare b as integer
11
12 set a = 0
13
14 if a = 0 then
15     set b = 1
16 end if
17
18 call myFunction
19
20 output a
21 output b
22 output c
23 output d
24
25 End MainProg
```

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- (a) State the outputs that this algorithm will give. [2]

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Examiner only

10. Two different types of search algorithm are binary search and linear search.

(a) The following is a binary search algorithm.

```

1  declare myArray[0 to 10]
2  declare start is integer
3  declare end is integer
4  declare found is Boolean
5  declare mid is integer
6
7  set start = 0
8  set end = 10
9  set found = FALSE
10
11 input searchValue
12
13 repeat
14     set mid = (start + end) DIV 2
15     if searchValue = myArray[mid] then
16         set found = TRUE
17         Output "searchValue found at position", mid
18     end if
19
20     if searchValue > myArray[mid] then
21         set start = mid + 1
22     end if
23
24     if searchValue < myArray[mid] then
25         set end = mid - 1
26     end if
27
28 until (found = TRUE) OR (end < start)
    
```

By crossing out or shading the discarded elements in the diagram below, show how the algorithm will reduce the part of the array being searched at each repetition.

searchValue = 22

[3]

	(0)	(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)	(9)	(10)
Original Data	12	22	27	31	38	54	63	71	73	87	92
Repetition 1	12	22	27	31	38	54	63	71	73	87	92
Repetition 2	12	22	27	31	38	54	63	71	73	87	92
Repetition 3	12	22	27	31	38	54	63	71	73	87	92

myArray

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10. The following algorithm calculates the area of a circle for a radius input by the user.

```
1  StarProc areaOfCircle
2  A is real
3  B is real
4  C is real
5
6  set C = 3.14
7
8  output "Please enter the radius"
9
10 input A
11
12 B = C * (A * A)
13
14 output "The Area is ", B
15
16 End Proc
```

(a) Identify and define the following terms in the algorithm above.

(i) Constant. [2]

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(ii) Variable. [2]

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(b) Describe why the use of self-documenting identifiers is important in programs and suggest suitable changes that you would make to the algorithm above to achieve this. [4]

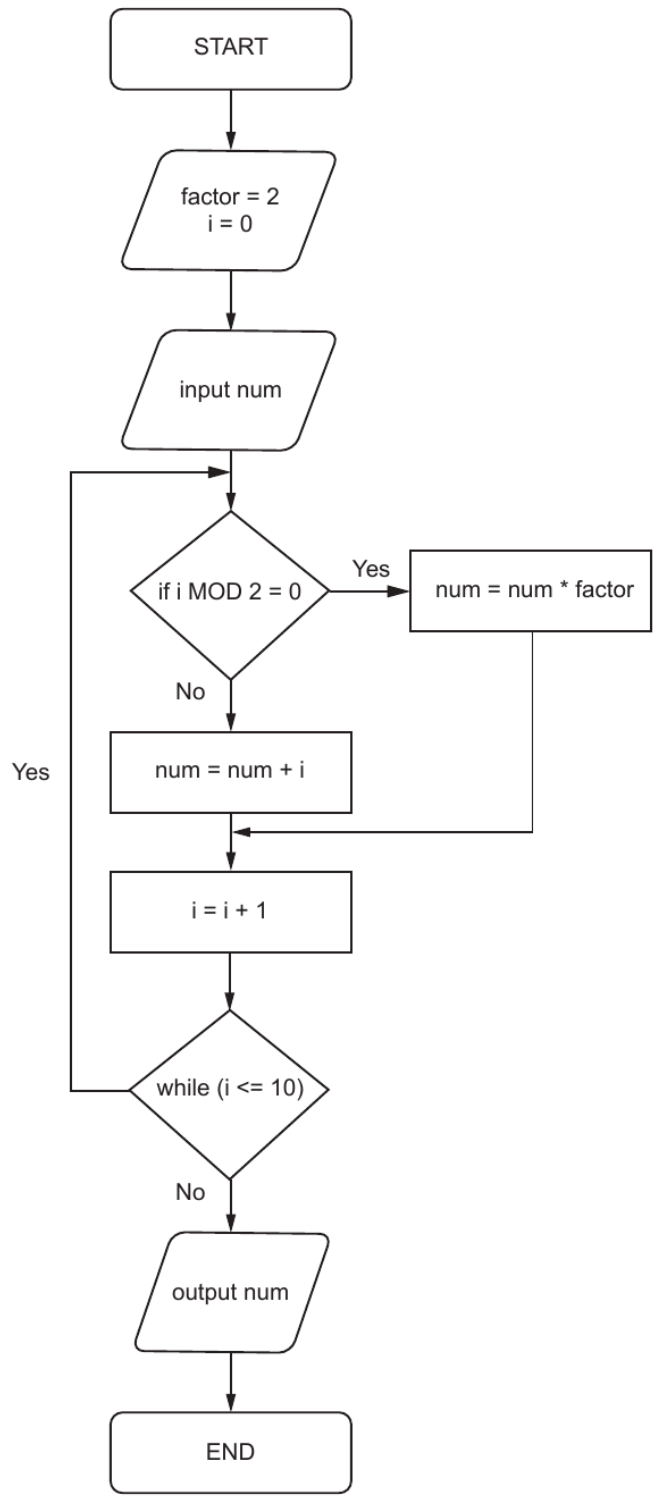
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9. Consider the constructs in the following algorithm.
Note: there is no need to dry-run the algorithm.



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Identify and describe the purpose of the following constructs in the algorithm:

(a) Constant. [2]

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(b) Variable. [2]

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(c) Selection. [2]

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(d) Repetition. [2]

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END OF QUESTION PACK

12 questions · 97 marks · ~2 h 26 min

Source: WJEC AS Computer Science Unit 1 (2500U10-1), Summer 2017–2024, COVID gap
Curated for WJEC Computer Science 2015 spec AS Unit 1 – Topic 6 (1.5)

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